

Identifiability in Dynamic Acyclic Networks with Partial Excitation and Measurement

Xiaodong Cheng¹ Shengling Shi² Paul M.J. Van den Hof²

¹ Control Group, Department of Engineering, University of Cambridge, UK

² Control Systems Group, Department of Electrical Engineering, TU Eindhoven, NL

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Outline

- 1 Introduction & Problem Setting
- 2 Previous Works
- 3 Main Results
- 4 Conclusion and Outlook

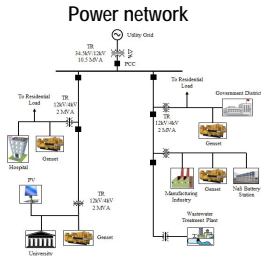
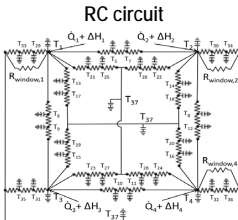
1 Introduction & Problem Setting

2 Previous Works

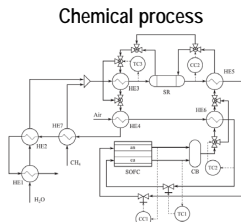
3 Main Results

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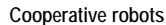
Appear in a wide range of applications

Chen, "Resilient Distribution Systems With
Community Microgrids" 2016

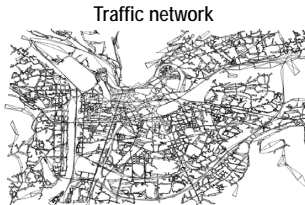
K. Deng et al, Automatica 2014



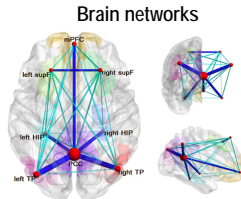
Heo, S., et al. Chemical Engineering Science, 2015



Robots in University of Groningen



N. Martin et al., IEEE NSE, 2019

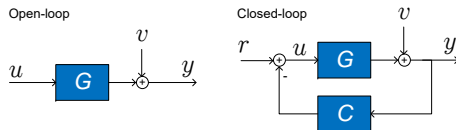


M. R. Knight IEEE Electrification Magazine 2016

Introduction

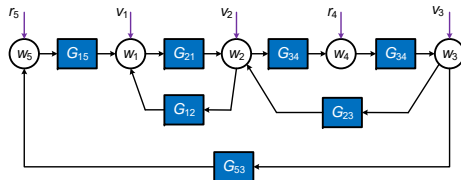
- Classical identification problems¹:

Identify a model of G based on measured signals u , y (and possibly r)



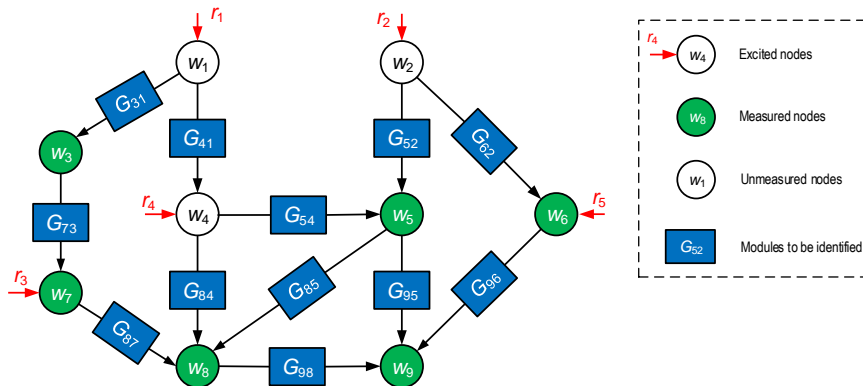
- How to address identification problems in a network setting?

To analyze **interconnection structure** of the signals.



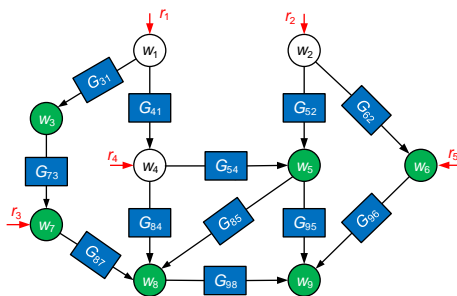
¹Ljung (1999), Pintelon and Schoukens (2012)

Dynamic Acyclic Networks



We concentrate on acyclic networks, i.e. there does not exist a pair of vertices that can reach each other.

Network Model Setting



A compact form of the overall network:

$$w(t) = G(q)w(t) + Rr(t) + v_e(t),$$

$$y(t) = Cw(t) + v_m(t),$$

- q^{-1} : delay operator
- $r(t)$, $y(t)$: measured external and internal signals
- R , C : indicate which nodes are excited and measured.

Assume:

- The network is *well-posed* and stable, i.e. $(I - G(q))^{-1}$ is proper and stable.
- All the entries of $G(q)$ are proper and stable transfer operators.

Network Identifiability

- From measurement data (r, y) , we obtain transfer function:

$$T_{C,\mathcal{R}} = C \underbrace{(I - G)^{-1}}_T R$$

²Weerts et al., SYSID2015; Weerts et al., Automatica, 2018;

³Bazanella, CDC2017; Hendrickx et al., IEEE-TAC, 2019.

Network Identifiability

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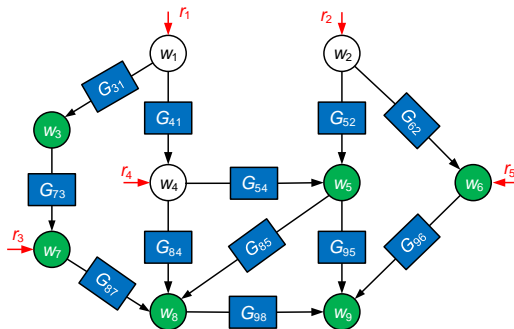
$$T_{C,\mathcal{R}} = C \underbrace{(I - G)^{-1}}_T R$$

- Consider a network model set $\mathcal{M} := \{M(q, \theta) = (G(q, \theta), R, C), \theta \in \Theta\}$,
Identifiability² of \mathcal{M} : *all the models (i.e. the entries of G) in \mathcal{M} can be distinguished from $T_{C,\mathcal{R}}$.*
- Generic identifiability**³: *almost all models in \mathcal{M} can be distinguished from $T_{C,\mathcal{R}}$ (excluding parameters that are in a subset of Θ with Lebesgue measure zero)*

²Weerts et al., SYSID2015; Weerts et al., Automatica, 2018;

³Bazanella, CDC2017; Hendrickx et al., IEEE-TAC, 2019.

Problems



- ① Under what conditions, the network model set is generically identifiable?
- ② Which nodes are measured/excited to achieve generic identifiability.

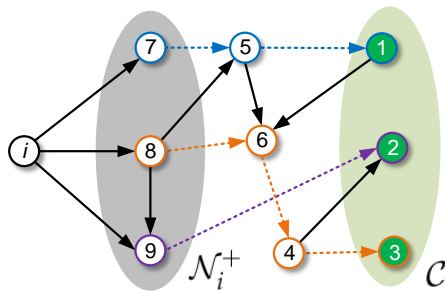
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Full Excitation - Path-Based Condition

Lemma (Path-based condition)

All transfer functions leaving node i is **generically identifiable** if and only if there are $|\mathcal{N}_i^+|$ **vertex disjoint paths** from \mathcal{N}_i^+ to \mathcal{C} .

The model set \mathcal{M} is **generically identifiable**, if the condition holds for all $i \in \mathcal{V}$.



- all the nodes are excited
- \mathcal{C} : the set of measured nodes
- \mathcal{N}_i^+ : the set of the out-neighbors of node i ;

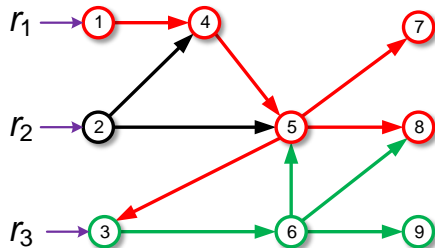
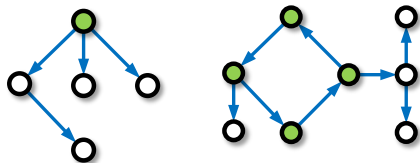
⁴Van der Woude, 1991, Hendrickx, Gevers & Bazanella, CDC 2017, Weerts et al., CDC 2018.

Full Measurement - Pseudotree-Covering Condition

Lemma (Pseudotree-Covering Condition⁴)

The network model set \mathcal{M} is **generically identifiable** if all the edges can be covered by a set of disjoint pseudotrees, and a root of each pseudotree is excited.

Pseudotrees: A connected directed graph with maximal indegree 1

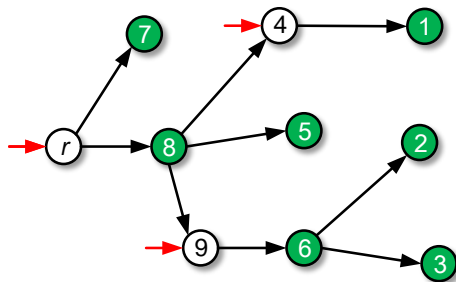


⁵Cheng et al., CDC2019; Cheng et al., IEEE-TAC2021

Partial Excitation/Measurement - Trees

Lemma (Trees⁵)

A tree is *generically identifiable* if and only if its *root is excited*, all the *leaves are measured*, and the *internal nodes are either excited or measured*.

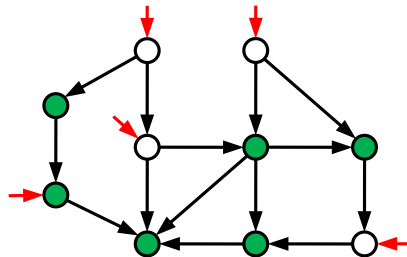
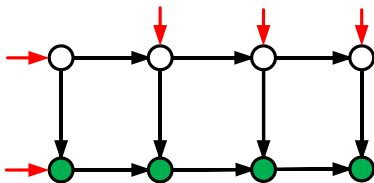


- **root**: the node has no in-neighbors
- **leaf**: the node has no out-neighbors
- **internal nodes**: the nodes that are neither root nor leaves

⁵Bazanella et al., CDC2019

General Acyclic Networks with Partial Excitation/Measurement

The above methods cannot be applied to acyclic networks:

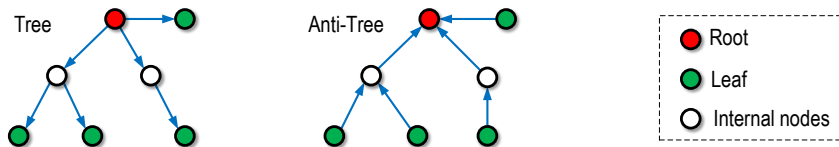


Problem

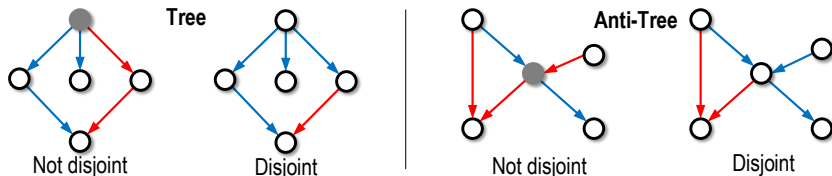
How to determine (generic) identifiability in acyclic networks?

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Disjoint Trees and Disjoint Anti-Trees



- Two trees (anti-trees) are **disjoint** if they **do not share common edges**, and all the **edges leaving from (pointing to) a node** are in the same tree (anti-trees).
- Any acyclic network can be decomposed into a set of disjoint trees or anti-trees

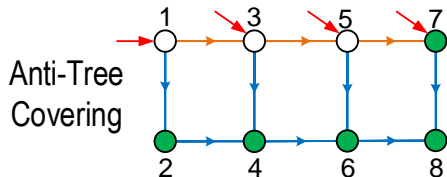
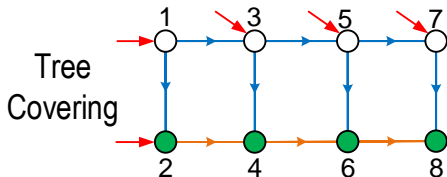


Generic Identifiability Condition

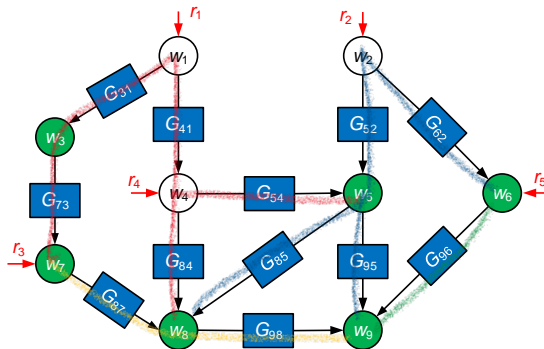
Theorem (Tree/Anti-tree covering)

Suppose that the underlying graph \mathcal{G} is acyclic with $\mathcal{V} = \mathcal{R} \cup \mathcal{C}$. Then, \mathcal{M} is **generically identifiable** if either of the following two conditions holds:

- 1 \mathcal{G} can be decomposed into a set of **disjoint trees**, and for each tree, its **root is excited** and all the **leaves are measured**.
- 2 \mathcal{G} can be decomposed into a set of **disjoint anti-trees**, and for each anti-tree, its **root is measured**, and all the **leaves are excited**.



Example



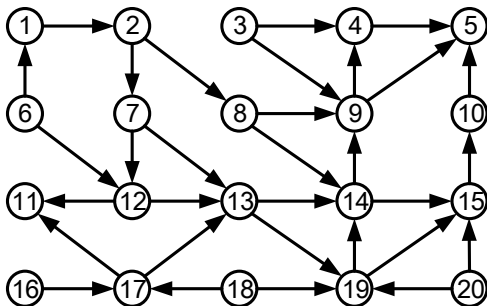
all the edges are covered by four trees ✓ roots are excited ✓ leaves are measured ✓

⇒ **identifiability**

Actuator/Sensor Allocation (Application of Condition 1)

Initialization:

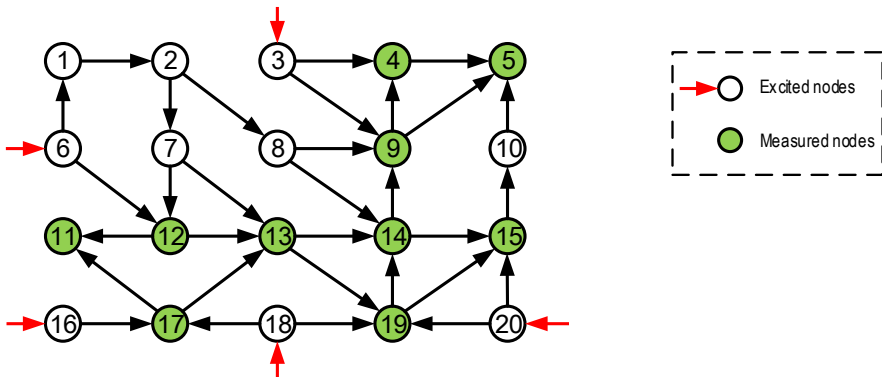
- All the sources are excited, and all the sinks are measured;
- Nodes having more than one in-neighbors are measured (implied by Condition 1).



Actuator/Sensor Allocation (Application of Condition 1)

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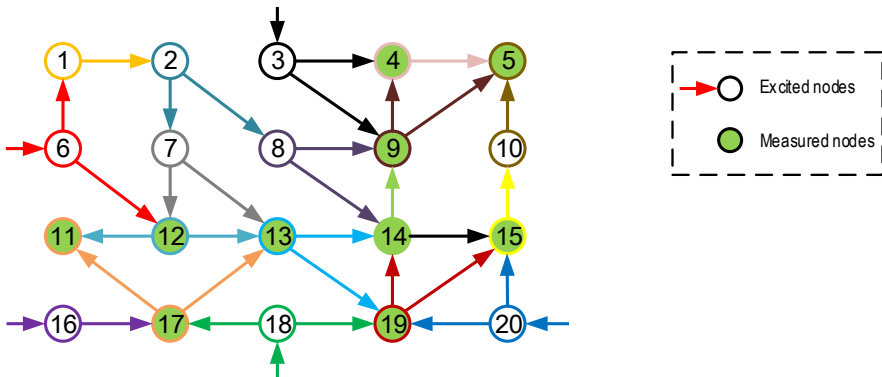
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Actuator/Sensor Allocation (Application of Condition 1)

A greedy tree merging procedure:

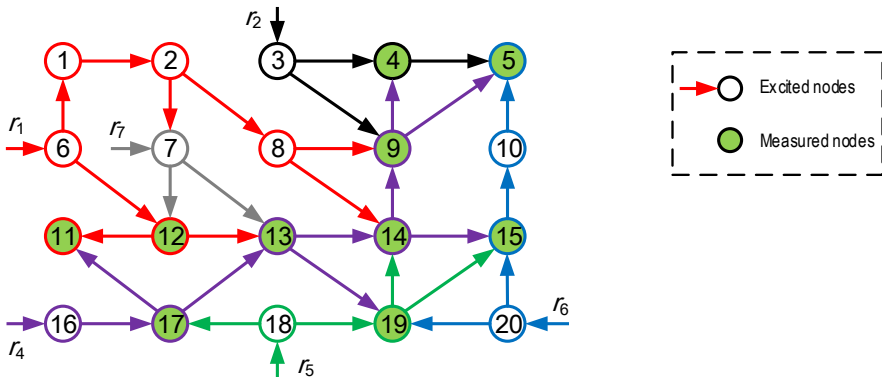
- Partition the graph into a set of smallest trees (i.e. a node with its out-going edges)
- Merge two trees if their union is still a tree



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- Extensions: cyclic networks contain known modules and correlated noise signals

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Thank you for your attention!